

# Initial-boundary value problem and stability of solutions for string baryon model “triangle”

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## Abstract

For the string baryon model “triangle” the initial-boundary value problem is stated and solved in general. This problem implies defining a classical motion of the system on the base of given initial position and initial velocities of string points. The presented solution reduces the initial-boundary value problem for the considered model to the system of ordinary differential equations that can be integrated numerically in general. Using this approach we ascertain the stability of the rotational motions (flat uniform rotations) for the “triangle” string configuration.

## Introduction

For describing orbitally excited baryons various string models are used. They differ from each other in the topology of spatial junction of three massive points (quarks) by relativistic strings. Four variants of this junction are possible (Fig.1): (a) the quark-diquark model  $q$ - $qq$  [1] (from the point of view of classical dynamics it coincides with the meson model of relativistic string with massive ends [2, 3]); (b) the linear configuration  $q$ - $q$ - $q$  [4, 5]; (c) the “three-string” model or Y-configuration [6, 7] and (d) the “triangle” model or  $\Delta$ -configuration [8, 9] that is under consideration in this paper.

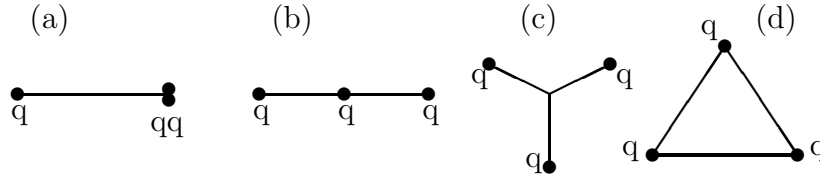


Figure 1: String baryon models.

The exact solutions of the classical equations of motion describing uniform rotations of the system are known for all these models. For the configurations  $q$ - $qq$  and  $q$ - $q$ - $q$  the rotating string has the form of a rectilinear segment [1, 2, 3]. For the “three-string” model there are

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three rectilinear segments joined in a plane at the angles  $120^\circ$  [6, 7]. For the model “triangle” the rotating string has the form of the closed curve consisting of segments of a hypocycloid [8, 9].

The connection between the energy of the system  $E = M$  and its angular momentum  $J$  for all these motions in the high energy limit (for any way of taking quark spins into account or neglecting quark spins) has the form [1, 4, 9, 10]

$$J \simeq \alpha' E^2, \quad J, E \rightarrow \infty. \quad (1)$$

This fact allows us to apply each of the mentioned models to describing the baryon states with large  $J$  on the Regge trajectories [4].

The problem of choosing the most adequate model among the four mentioned ones is not solved yet. For the q-q-q and q-q-q configurations the Regge slope  $\alpha'$  in Eq. (1) is connected with the string tension  $\gamma$  by the Nambu relation  $\alpha' = (2\pi\gamma)^{-1}$  [11] and the tension should be equal for mesons and baryons. The configurations Y and  $\Delta$  describe the Regge trajectories if the effective tension  $\gamma$  for them is lower than the “mesonic” tension  $\gamma \simeq 0.18 \text{ GeV}^2$  [4].

On the other hand the QCD-motivated baryon Wilson loop operator approach gives some arguments in favour of the Y-configuration [12] or the “triangle” model [13].

When we choose the adequate string baryon configuration we are also take into account the stability of rotational motions for these systems. In particular, the rotational motions of the q-q-q system with the middle quark at rest are unstable with respect to centrifugal moving away of the middle quark [5]. Any small disturbance results in a complicated quasiperiodic motion, but the system doesn't transform into the quark-diquark one [1]. The latter q-q-q configuration (or the meson string model) seems to be stable but this question is not exhaustively studied. Small disturbances of the well known exact solution (uniformly rotating rectilinear string) result in a rotation of the string with slightly varying shape and interquark distance [14]. Some small corrections to the meson string rotational motions are searched in Refs. [15].

The stability problem for the other string baryon models (Fig.1) wasn't studied. In this paper we investigate in this respect the hypocycloidal rotational motions in the model “triangle” [8, 9].

There is the opinion that an orbitally excited baryon system with the given momentum  $J$  “chooses” the only steady state with the lowest energy [1]. In according with this statement the simplest nontrivial rotational motion in the model “triangle” (three quarks connected by smooth segments of hypocycloids) should transform into the “quark-diquark” state [9] with two quarks merging into one.

The simplest way to solve the stability problem is to develop a method of solution of the initial-boundary value problem with arbitrary initial conditions for the “triangle” model. Such a method is suggested in this paper.

In Sect.1 the equations of motion with their common solution and the boundary conditions for the string baryon model “triangle” are given. In Sect.2 the solution of the initial-boundary value problem is suggested. It develops the approach used earlier for the meson string model with massive ends [16] and for the q-q-q baryon configuration [5]. In the last section the stability of the rotational motions is verified.

# 1 Dynamics of string baryon model “triangle”

Let us consider a closed relativistic string with the tension  $\gamma$  carrying three pointlike masses  $m_1, m_2, m_3$ . The action for this system is [8, 9]

$$S = -\gamma \int_{\tau_1}^{\tau_2} d\tau \int_{\sigma_0(\tau)}^{\sigma_3(\tau)} \sqrt{-g} d\sigma - \sum_{i=1}^3 m_i \int_{\tau_1}^{\tau_2} \left\{ \left[ \frac{d}{d\tau} X^\mu(\tau, \sigma_i(\tau)) \right]^2 \right\}^{1/2} d\tau. \quad (2)$$

Here  $X^\mu(\tau, \sigma)$  are coordinates of a point of the string in  $D$ -dimensional Minkowski space  $R^{1,D-1}$  with signature  $+, -, -, \dots$ ,  $g = \dot{X}^2 X'^2 - (\dot{X} X')^2$  ( $\tau, \sigma \in \Omega = \Omega_0 \cup \Omega_1 \cup \Omega_3$  (Fig. 2),  $(a, b) = a^\mu b_\mu$  is the (pseudo)scalar product,  $\dot{X}^\mu = \partial_\tau X^\mu$ ,  $X'^\mu = \partial_\sigma X^\mu$ , the speed of light  $c = 1$ ;  $\sigma_i(\tau)$  are inner coordinates of the quark world lines<sup>1</sup>,  $i = 0, 1, 2, 3$ .

The equations  $\sigma = \sigma_0(\tau)$  and  $\sigma = \sigma_3(\tau)$  determine the trajectory of the same (third) quark. It is connected with the fact that string is closed and may be written in the following general form [8]:

$$X^\mu(\tau, \sigma_0(\tau)) = X^\mu(\tau^*, \sigma_3(\tau^*)). \quad (3)$$

The parameters  $\tau$  and  $\tau^*$  in these two parametrizations of just the same line are not equal in general.

Variation and minimization of action (2) result in the equations of motion of the string and the boundary conditions at the quark trajectories. These trajectories are smooth curves. Derivatives of  $X^\mu$  can have discontinuities on the lines  $\sigma = \sigma_i(\tau)$  (except for tangential).

However, through a nondegenerate reparametrization  $\tau = \tau(\tilde{\tau}, \tilde{\sigma})$ ,  $\sigma = \sigma(\tilde{\tau}, \tilde{\sigma})$  the induced metric on the world surface of the string may be made continuous and conformally flat [8], i.e., satisfying the orthonormality conditions

$$\dot{X}^2 + X'^2 = 0, \quad (\dot{X}, X') = 0. \quad (4)$$

Under conditions (4) the equations of motion become linear

$$\ddot{X}^\mu + X''^\mu = 0, \quad (5)$$

and the boundary conditions take the simplest form [8, 9]

$$m_i \frac{d}{d\tau} U_i^\mu(\tau) - \gamma [X'^\mu + \sigma'_i(\tau) \dot{X}^\mu] \Big|_{\sigma=\sigma_i+0} + \gamma [X'^\mu + \sigma'_i(\tau) \dot{X}^\mu] \Big|_{\sigma=\sigma_i-0} = 0. \quad (6)$$

Here the notation

$$U_i^\mu(\tau) = \frac{\dot{X}^\mu + \sigma'_i(\tau) X'^\mu}{\sqrt{\dot{X}^2 \cdot (1 - \sigma_i'^2)}} \Big|_{\sigma=\sigma_i(\tau)} \quad (7)$$

for unit  $R^{1,D-1}$ -velocity vector of  $i$ -th quark is used.

In accordance with the closure condition (3) for the third quark  $i = 3$  one should put  $\sigma = \sigma_0(\tau)$  in the second summand in Eq. (6) and replace  $\tau$  by  $\tau^*$  in the last term.

At this stage we have five undetermined functions in this model:  $\tau^*(\tau)$  in the closure condition (3) and four trajectories  $\sigma_i(\tau)$ ,  $i = 0, 1, 2, 3$ . Using the fact that Eqs. (4)–(6) are invariant with respect to the reparametrizations [3]

$$\tau \pm \sigma = f_\pm(\tilde{\tau} \pm \tilde{\sigma}). \quad (8)$$

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<sup>1</sup>We use the term “quark” instead of “material point” for brevity, keeping in mind that the considered model on the classic level doesn’t describe the spin and other quantum numbers of quarks.

we fix two<sup>2</sup> of the mentioned functions as follows (Fig. 2):

$$\sigma_0(\tau) = 0, \quad \tau^*(\tau) = \tau. \quad (9)$$

The first Eq. (9) may be obtained at the first step through the above reparametrization (8) with the required  $f_+$  and  $f_-(\eta) = \eta$ . At the second step one can get the equality  $\tau^* = \tau$  by repeating the procedure (8) with the function  $f_+ = f_- \equiv f$  that satisfies the condition

$$2f(\tau) = f(\tau^*(\tau) + \sigma_3(\tau)) + f(\tau^*(\tau) - \sigma_3(\tau)).$$

The equality  $\tau^*(\tau) = \tau$  is equivalent to the closure of any coordinate line  $\tau = \text{const}$  on the world surface.

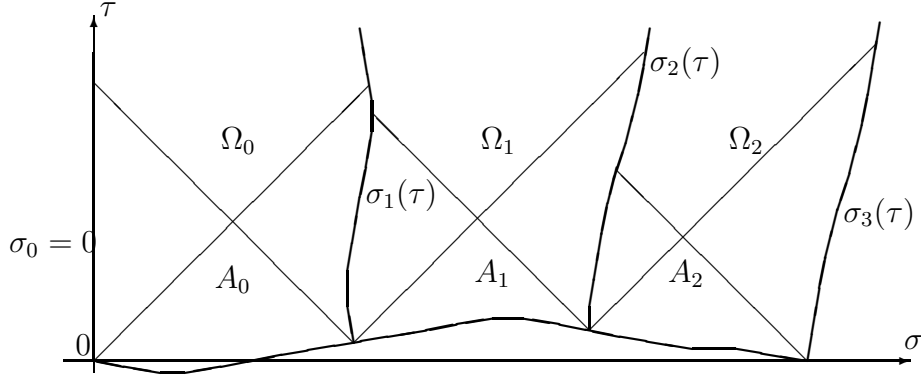


Figure 2: The domain  $\Omega$  and the initial curve.

The domain  $\Omega$  is divided into three ones  $\Omega_i = \{(\tau, \sigma) : \sigma_i(\tau) < \sigma < \sigma_{i+1}(\tau)\}$ ,  $i = 0, 1, 2$  (Fig. 2) by the quark trajectories. The general solutions of Eq. (5) in these domains are described by different functions

$$X^\mu(\tau, \sigma) = \frac{1}{2}[\Psi_{i+}^\mu(\tau + \sigma) + \Psi_{i-}^\mu(\tau - \sigma)], \quad (\tau, \sigma) \in \Omega_i, \quad i = 0, 1, 2. \quad (10)$$

It is the consequence of discontinuities of  $X^\mu$  at  $\sigma = \sigma_i(\tau)$ . Nevertheless, the function  $X^\mu$  and its tangential derivative  $\frac{d}{d\tau}X^\mu(\tau, \sigma_i(\tau))$  are continuous on the lines  $\sigma_i(\tau)$ . It results in the relations

$$\Psi_{(i-1)+}^\mu(+) + \Psi_{(i-1)-}^\mu(-) = \Psi_{i+}^\mu(+) + \Psi_{i-}^\mu(-), \quad (11)$$

$$\frac{d}{d\tau}[\Psi_{(i-1)+}^\mu(+) + \Psi_{(i-1)-}^\mu(-)] = \frac{d}{d\tau}[\Psi_{i+}^\mu(+) + \Psi_{i-}^\mu(-)]. \quad (12)$$

We use here and below the notations  $(+) \equiv (\tau + \sigma_i(\tau))$ ,  $(-) \equiv (\tau - \sigma_i(\tau))$ .

For the third quark ( $i = 3$ ) the equality (11) is the closure condition (3). Under conditions (9) this equality takes the form

$$\Psi_{2+}^\mu(\tau + \sigma_3(\tau)) + \Psi_{2-}^\mu(\tau - \sigma_3(\tau)) = \Psi_{0+}^\mu(\tau) + \Psi_{0-}^\mu(\tau).$$

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<sup>2</sup>The remaining three functions will be calculated with solving the initial-boundary value problem in Sects. 2, 3.

Similarly, for  $i = 3$  in the r.h.s. of (12) and anywhere below one should replace the expressions  $(1 \pm \sigma_3)\Psi'_{3\pm}(\pm)$  by  $\Psi'_{0\pm}(\tau)$  in accordance with the conditions (3) and (9).

If we substitute the general solution (10) into the boundary conditions (6) and Eq. (7) these equations take the form

$$\frac{dU_i^\mu(\tau)}{d\tau} + \frac{\gamma}{2m_i} \left[ (1 + \sigma'_i) [\Psi'_{(i-1)+}^\mu(+) - \Psi'_{i+}^\mu(+)] + (1 - \sigma'_i) [\Psi'_{i-}^\mu(-) - \Psi'_{(i-1)-}^\mu(-)] \right] = 0, \quad (13)$$

$$U_i^\mu(\tau) = \frac{(1 + \sigma'_i) \Psi'_{(i-1)+}^\mu(+) + (1 - \sigma'_i) \Psi'_{(i-1)-}^\mu(-)}{\sqrt{2(1 - \sigma_i'^2)(\Psi'_{(i-1)+}^\mu(+), \Psi'_{(i-1)-}^\mu(-))}} = \frac{(1 + \sigma'_i) \Psi'_{i+}^\mu(+) + (1 - \sigma'_i) \Psi'_{i-}^\mu(-)}{\sqrt{2(1 - \sigma_i'^2)(\Psi'_{i+}^\mu(+), \Psi'_{i-}^\mu(-))}}. \quad (14)$$

## 2 Initial-boundary value problem

The initial-boundary value problem for the “triangle” string configuration is reduced to obtaining the solution of Eq. (5) sufficiently smooth [5, 16] in the domain  $\Omega = \bigcup_i \Omega_i$  and satisfying the orthonormality conditions (4), boundary conditions (6) and two given initial conditions: an initial position of the string in Minkowski space and initial velocities of string points.

An initial position of the string can be given as a curve in Minkowski space

$$x^\mu = \rho^\mu(\lambda), \quad \lambda \in [\lambda_0, \lambda_3]. \quad (15)$$

This curve is space-like ( $[\rho'(\lambda)]^2 < 0$ ) and closed:  $\rho^\mu(\lambda_0) = \rho^\mu(\lambda_3)$ . The function  $\rho^\mu(\lambda)$  is piecewise smooth,  $\rho'^\mu$  may have discontinuities at the quark positions  $\lambda = \lambda_1, \lambda_2$ .

Initial velocities on the initial curve can be given as a time-like vector  $v^\mu(\lambda)$ ,  $\lambda \in [\lambda_0, \lambda_3]$ ,  $v^\mu(\lambda)$  may be multiplied by an arbitrary scalar function  $\phi(\lambda) > 0$ . The condition  $v^\mu(\lambda_0) = v^\mu(\lambda_3) \cdot \text{const}$  is fulfilled.

To solve the problem we set parametrically the initial curve (15) on the world surface (Fig. 2)

$$\tau = \tau(\lambda), \quad \sigma = \sigma(\lambda), \quad \lambda \in [\lambda_0, \lambda_3]$$

and use the following general form for the initial position and velocities [16]:

$$X^\mu(\tau(\lambda), \sigma(\lambda)) = \rho^\mu(\lambda), \quad (16)$$

$$\alpha(\lambda) \dot{X}^\mu(\tau(\lambda), \sigma(\lambda)) + \beta(\lambda) X'^\mu(\tau(\lambda), \sigma(\lambda)) = v^\mu(\lambda). \quad (17)$$

Here  $\alpha(\lambda)$ ,  $\beta(\lambda)$  are arbitrary functions satisfying the inequality  $\alpha(\lambda) > |\beta(\lambda)|$ .

Functions  $\tau(\lambda)$ ,  $\sigma(\lambda)$ ,  $\alpha(\lambda)$ ,  $\beta(\lambda)$  are related by the formulas [16]

$$\sigma'(\lambda) = \frac{\alpha\Delta + \beta P}{v^2}, \quad \tau'(\lambda) = \frac{\beta\Delta + \alpha P}{v^2}, \quad (18)$$

where  $P(\lambda) = (v(\lambda), \rho'(\lambda))$ ,  $\Delta(\lambda) = \sqrt{(v, \rho')^2 - v^2 \rho'^2}$ .

The freedom in choosing the functions  $\alpha(\lambda)$ ,  $\beta(\lambda)$  or  $\tau(\lambda)$  and  $\sigma(\lambda)$  is connected with the existence of the class of the reparametrizations (8) preserving the conditions (9) [17]. When

we choose the functions  $\alpha(\lambda)$ ,  $\beta(\lambda)$  we take into account only the inequality  $\alpha > |\beta|$  and conditions (9) resulting in the constraints for  $\beta(\lambda)$  and  $\tau(\lambda)$

$$\beta(\lambda_0) = 0, \quad \sigma(\lambda_0) = 0, \quad \tau(\lambda_0) = \tau(\lambda_3) = 0. \quad (19)$$

One may obtain the equalities  $\tau(\lambda_0) = \sigma(\lambda_0) = 0$  (Fig. 2) by choosing the constants of integration in Eq. (18), and the equality  $\tau(\lambda_0) = \tau(\lambda_3)$  in (19) — through multiplying  $\alpha(\lambda)$  or  $\beta(\lambda)$  by a constant.

Using the formulas [16]

$$\Psi'_{i\pm}{}^\mu(\tau(\lambda) \pm \sigma(\lambda)) = \frac{(\Delta \mp P)v^\mu \pm v^2 \rho'^\mu}{\Delta(\alpha(\lambda) \pm \beta(\lambda))} \quad (20)$$

we can determine the functions  $\Psi'_{i\pm}{}^\mu$  from the initial data in the following finite segments:

$$\begin{aligned} \Psi'_{i+}{}^\mu(\xi), \quad & \xi \in [\tau(\lambda_i) + \sigma(\lambda_i), \tau(\lambda_{i+1}) + \sigma(\lambda_{i+1})], \\ \Psi'_{i-}{}^\mu(\xi), \quad & \xi \in [\tau(\lambda_{i+1}) - \sigma(\lambda_{i+1}), \tau(\lambda_i) - \sigma(\lambda_i)], \end{aligned} \quad (21)$$

that lets us find the solution of the problem in the form (10) in the zones (Fig. 2)

$$A_i = \{(\tau, \sigma) : \tau(\lambda) < \tau \leq \sigma + \tau(\lambda_i) - \sigma(\lambda_i); \tau + \sigma \leq \tau(\lambda_{i+1}) + \sigma(\lambda_{i+1})\}.$$

In these zones the solution depends only on initial data without influence of the boundaries. The integration constants in Eq. (20) are determined from the initial condition (16). In others parts of the domains  $\Omega_i$  the solution will be obtained by the prolongation of the functions  $\Psi'_{i\pm}{}^\mu$  with the help of the boundary conditions (13), (14).

We transform the systems of the ordinary differential equations (13), (14) to the normal form by the method used in the paper [16].

Multiplying scalarly Eq. (14) by  $(1 \pm \sigma'_i) \Psi'_{(i-1)\pm}{}^\mu(\pm)$ ,  $(1 \pm \sigma'_i) \Psi'_{i\pm}{}^\mu(\pm)$  and taking into account the isotropy of the vectors  $\Psi'_{i\pm}{}^\mu$

$$\Psi'^2_{i+}(\tau) = \Psi'^2_{i-}(\tau) = 0, \quad i = 0, 1, 2,$$

(resulting from conditions (4)) we obtain the equalities

$$\begin{aligned} \frac{1}{\sqrt{2}} \sqrt{(1 - \sigma'^2_i)(\Psi'_{(i-1)+}{}^\mu(+), \Psi'_{(i-1)-}{}^\mu(-))} &= (1 + \sigma'_i)(U_i(\tau), \Psi'_{(i-1)+}{}^\mu(+)) = \\ &= (1 - \sigma'_i)(U_i(\tau), \Psi'_{(i-1)-}{}^\mu(-)) = \frac{1}{\sqrt{2}} \sqrt{(1 - \sigma'^2_i)(\Psi'_{i+}{}^\mu(+), \Psi'_{i-}{}^\mu(-))} = \\ &= (1 + \sigma'_i)(U_i(\tau), \Psi'_{i+}{}^\mu(+)) = (1 - \sigma'_i)(U_i(\tau), \Psi'_{i-}{}^\mu(-)). \end{aligned} \quad (22)$$

Eqs. (14) and (22) result in the relations

$$(1 + \sigma'_i) \Psi'_{j+}{}^\mu(+) + (1 - \sigma'_i) \Psi'_{j-}{}^\mu(-) = 2(1 \pm \sigma'_i)(U_i(\tau), \Psi'_{k\pm}{}^\mu(\pm)) U_i^\mu(\tau)$$

taking place for all 8 variants of choosing  $j$ ,  $k$  equal to  $i$  or  $i - 1$  and the sign  $\pm$ . The latter relations let us transform the summands in (13) as follows:

$$\begin{aligned} (1 + \sigma'_i) \Psi'_{(i-1)+}{}^\mu(+) - (1 - \sigma'_i) \Psi'_{(i-1)-}{}^\mu(-) &= 2(1 - \sigma'_i) \Psi'^\nu_{(i-1)-}(-)(U_i^\mu U_{i\nu} - \delta^\mu_\nu), \\ (1 - \sigma'_i) \Psi'_{i-}{}^\mu(-) - (1 + \sigma'_i) \Psi'_{i+}{}^\mu(+) &= 2(1 + \sigma'_i) \Psi'^\nu_{i+}(+)(U_i^\mu U_{i\nu} - \delta^\mu_\nu). \end{aligned}$$

where  $\delta_\nu^\mu = \begin{cases} 1, & \mu = \nu \\ 0, & \mu \neq \nu. \end{cases}$  Eqs. (13) take the normal form now

$$\frac{dU_i^\mu}{d\tau} = \frac{\gamma}{m_i} [\delta_\nu^\mu - U_i^\mu(\tau) U_{i\nu}(\tau)] [(1 + \sigma'_i) \Psi_{i+}^{\nu'}(+) + (1 - \sigma'_i) \Psi_{(i-1)-}^{\nu'}(-)]. \quad (23)$$

As was mentioned above for  $i = 3$  in Eq. (23) one should replace  $(1 + \sigma'_3) \Psi_{3+}^\mu(+)$  by  $\Psi_{0+}^\mu(\tau)$  in accordance with Eqs. (3) and (9). The systems (23) need the initial conditions

$$U_i^\mu(\tau(\lambda_i)) = v^\mu(\lambda_i) / \sqrt{v^2(\lambda_i)}, \quad i = 1, 2, 3. \quad (24)$$

Integrating systems (23) with the initial conditions (24) we can determine unknown vector functions  $U_i^\mu(\tau)$  for  $\tau > \tau(\lambda_i)$  with the help of the functions  $\Psi_{i\pm}^{\mu'}$  known from the initial data on the segments (21). This procedure is limited in  $\tau$  by the ordinates of the points in which the trajectories  $\sigma = \sigma_i(\tau)$  cross the characteristic lines  $\tau \pm \sigma = \text{const}$  (Fig. 2). However we can continue this procedure for all  $\tau$  if for every value of  $\tau$  (after calculating  $U_i^{\mu'}$  from Eq. (23)) we determine the functions  $\Psi_{i\pm}^{\mu'}$  outside segments (21) with the help of Eq. (13).

For this purpose we express functions  $\Psi_{(i-1)+}^{\mu'}$  and  $\Psi_{i-}^{\mu'}$  from Eqs. (12) and (13)

$$\begin{aligned} \Psi_{(i-1)+}^{\mu'}(\tau + \sigma_i) &= \Psi_{i+}^{\mu'}(\tau + \sigma_i) - m_i [\gamma(1 + \sigma'_i)]^{-1} U_i^{\mu'}(\tau), \\ \Psi_{i-}^{\mu'}(\tau - \sigma_i) &= \Psi_{(i-1)-}^{\mu'}(\tau - \sigma_i) - m_i [\gamma(1 - \sigma'_i)]^{-1} U_i^{\mu'}(\tau), \end{aligned} \quad i = 1, 2. \quad (25)$$

The similar relations for  $i = 3$  are

$$\begin{aligned} \Psi_{2+}^{\mu'}(\tau + \sigma_3) &= (1 + \sigma'_3)^{-1} [\Psi_{0+}^{\mu'}(\tau) - m_3 \gamma^{-1} U_3^{\mu'}(\tau)], \\ \Psi_{0-}^{\mu'}(\tau) &= (1 - \sigma'_3) \Psi_{2-}^{\mu'}(\tau - \sigma_3) - m_3 \gamma^{-1} U_3^{\mu'}(\tau). \end{aligned}$$

For solving the system (23) we are to determine the functions  $\sigma_i(\tau)$  for  $\tau > \tau(\lambda_i)$ . These functions may be obtained by taking some of the equalities (22)

$$(1 - \sigma'_i)(U_i(\tau), \Psi_{(i-1)-}^{\nu'}(-)) = (1 + \sigma'_i)(U_i(\tau), \Psi_{i+}^{\nu'}(+))$$

and expressing  $\sigma'_i$  in the following way (separately for  $i = 1, 2$  and  $i = 3$ ):

$$\frac{d\sigma_i}{d\tau} = \frac{(U_i, [\Psi_{(i-1)-}^{\nu'}(-) - \Psi_{i+}^{\nu'}(+)])}{(U_i, [\Psi_{(i-1)-}^{\nu'}(-) + \Psi_{i+}^{\nu'}(+)]), \quad \frac{d\sigma_3}{d\tau} = 1 - \frac{(U_3, \Psi_{0+}^{\nu'}(\tau))}{(U_3, \Psi_{2-}^{\nu'}(\tau - \sigma_3))}. \quad (26)$$

The equations and systems (23)–(26) allow us to continue the functions  $\Psi_{i\pm}^{\mu'}$  determined from the initial conditions through Eqs. (20) on the segments (21). The constants of integration in  $\Psi_{i\pm}^{\mu'}$  are fixed from Eq. (16). This algorithm of calculating  $\Psi_{i\pm}^{\mu'}$  (with taking into account Eq.(10)) solves the considered initial-boundary value problem with arbitrary initial conditions  $\rho^\mu(\lambda)$ ,  $v^\mu(\lambda)$ .

### 3 Stability of the rotational motions

For the model “triangle” the exact solutions of the equations of motion (4), (5), (6) describing the flat uniform rotation of the system (with the quarks connected by hypocycloidal segments of the strings) are known [8, 9]. World surfaces with the parametric representation  $\sigma_i(\tau) =$

$\sigma_i = \text{const}$  and the form of closure condition (3)  $\tau^* - \tau = T = \text{const}$  may be represented as follows ( $X^1 \equiv x$ ,  $X^2 \equiv y$ ):

$$X^0 = \tau - \frac{T}{\sigma_3 - \sigma_0} \sigma, \quad X^1 + iX^2 = u(\sigma) e^{i\omega\tau}. \quad (27)$$

Here  $u(\sigma) = A_i \cos \omega\sigma + B_i \sin \omega\sigma$ ,  $\sigma \in [\sigma_i, \sigma_{i+1}]$ ;  $\omega$  is the angular frequency of this rotation. Real  $(\sigma_i, T, \omega, m_i/\gamma)$  and complex  $(A_i, B_i)$  constants are connected by certain relations [8, 9, 18]. Topologically different types of solutions (27) are characterized, in particular, by the integer parameters  $n$  and  $k$ , defined by the relations (if there are no singularities  $\dot{X}^2 = 0$  in the segment  $[\sigma_0, \sigma_1]$ ):

$$n = \lim_{m_i \rightarrow 0} \frac{\sigma_3 - \sigma_0}{\sigma_1 - \sigma_0}, \quad k = \lim_{m_i \rightarrow 0} \frac{T}{\sigma_1 - \sigma_0}.$$

These values are equal to  $n = 3$ ,  $|k| = 1$  for the simple states in which three quarks are connected by smooth segments of hypocycloids. As we have said in the introduction the question about stability of such motions remains open.

The above described method gives possibility to obtain (numerically, in general) the world surface (27) as the solution of certain initial-boundary value problem and also to research the stability of these motions solving the problem with disturbed initial conditions  $\rho^\mu(\lambda)$  and  $v^\mu(\lambda)$ . As the simplest variations of initial conditions for the model “triangle” we consider an initial position of the string in the form of a rectilinear triangle with the base  $a$  and the altitude  $h$  in the  $xy$  plain. Initial velocities  $v^\mu(\lambda)$  correspond to the uniform rotation of the system with the angular frequency  $\vec{\omega} = \{0; 0; \omega\}$  about the center with coordinates  $\vec{\rho}_c$  ( $\vec{\rho}$ ,  $\vec{v}$  are notations for three-dimensional vectors in  $R^3$ , the time coordinate in Minkowski space is  $\rho^0(\lambda) = 0$ ,  $v^0(\lambda) = 1$ ):

$$\rho^1(\lambda) = \begin{cases} a\lambda, \\ a - b(\lambda - 1), \\ (a - b)(3 - \lambda); \end{cases} \quad \rho^2(\lambda) = \begin{cases} 0, & 0 \leq \lambda \leq 1, \\ h(\lambda - 1), & 1 \leq \lambda \leq 2, \\ h(3 - \lambda), & 2 \leq \lambda \leq 3; \end{cases} \quad (28)$$

$$\rho^3(\lambda) = 0; \quad \vec{v}(\lambda) = [\vec{\omega} \times (\vec{\rho} - \vec{\rho}_c)].$$

The quarks are placed at the corners of the triangle  $\lambda_0 = 0$ ,  $\lambda_1 = 1, \dots$

The systems of equations (23), (25), (26) are analytically solvable only in some exceptional cases. Arbitrary initial conditions, in particular, the conditions (28) require numerical methods. The numerical procedure of solving the initial-boundary value problem for the relativistic string with massive ends is described in the paper [14], the model q-q-q (technically more difficult) is considered in Ref. [5].

In the present work we mention only the main points of our calculations. At first we determine functions  $\Psi_{i\pm}''$  on the segments (21) by formulas (20). Then we integrate the systems (23) simultaneously for all  $i$  with the initial conditions (24) and continue the functions  $\Psi_{i\pm}''$  with the help of expressions (25).

The results of computing are represented as projections of the world surface level lines  $t = X^0(\tau, \sigma) = \text{const}$  at the  $xy$  plain. This “photos” of sequential positions of the system are made with the step in time  $\Delta t$ . For pictorial simplicity we consider only flat motions.

With an illustrative view the solution of the initial-boundary value problem for the model “triangle” is represented in Fig. 3. Here the parameters are:  $m_1 = m_2 = m_3 = 1$ ,  $\gamma = 1$ , the initial position of the string has the form of the equilateral triangle with  $a = 1$  and with



zero initial speed of the string points, that is with initial conditions (28) where  $a = 2b = 2h/\sqrt{3} = 1$ ,  $\vec{v} = \vec{\omega} = 0$ .

In Figs. 3a–3d the positions of the system are numbered in order of increasing  $t$  with the step in time  $\Delta t = 0.125$ . The position of the 3-th quark is marked by a circle. Owing to the symmetry of the system the quarks move along the three straight lines while the motion of the string is rather complicated.

Let us turn to the stability testing of the rotational motions (27). We consider the initial conditions (28) slightly disturbing these motions.

The detailed analysis of the problem was made for various parameters of the model and initial conditions. The typical example of the solution of the initial-boundary value problem for the “triangle” model with close but different masses and initial conditions (28) is represented in Fig. 4. We take the following parameters:

$$\begin{aligned} m_1 = 1, \quad m_2 = 1.5, \quad m_3 = 1.2, \quad \gamma = 1, \quad \Delta t = 0.15, \\ a = 2b = 0.5, \quad h = 0.33, \quad \vec{\rho}_c = \{a/2; h/3\}, \quad \omega = 2. \end{aligned} \quad (29)$$

The origin of the coordinates in Fig. 4 coincides with the rotational center (with the position vector  $\vec{\rho}_c$ ). The values  $\rho^\mu(\lambda)$  and  $v^\mu(\lambda)$  (29) are close to those which give the exact hypocycloidal solution (27) for this system (with the same  $m_i$ ,  $\gamma$  and the angular velocity  $\omega = 2$ ). The last solution describes the uniform rotation of the system with the string shape that is x-marked in Fig. 4a. The string positions for the solutions (28)–(29) are represented by continuous lines. The positions of the third quark with  $m_3 = 1.2$  are marked by circles and numbered as in Fig. 3.

The further evolution of the system is represented in Figs. 4b–4d (some time interval between Figs. 4c and 4d is omitted for the sake of space economy).

We see that when the system rotates the distances between the quarks and the configuration of the string segments change and fluctuate near the values corresponding to the motion (27) (x-marks in Fig. 4a).

This and a lot of other numerical experiments (with various values  $m_i$ , the energy,  $\rho^\mu(\lambda)$ ,  $v^\mu(\lambda)$  and various types of disturbances) show that the simple rotational motions (27) with  $n = 3$ ,  $|k| = 1$  are stable. That is small perturbations don’t grow in time<sup>3</sup>.

We are to emphasize that the simple motions (27) are steady with respect to transforming into the “quark-diquark” states with  $n = 2$ ,  $k = 0$  [9] and merging two quarks into the diquark. One may obtain this transformation only through rather strong disturbances<sup>4</sup>, for example, by reducing one of the sides of the triangle (28). In particular, for the system with  $m_1 = m_2 = m_3$  and initial quark speeds  $v = 0.5$  the motion remains “simple” (similar to that in Fig. 4) if the relation  $h/a$  of the triangle (28) with  $b = a/2$  does not exceed the rather large critical value  $(h/a)_{cr} \simeq 2.93$ .

In Fig. 5 one can see the evolution of the described system ( $m_i$ ,  $\gamma$ ,  $\vec{\rho}_c$ ,  $\omega$  correspond to the initial quark speeds  $v = 0.5$ ) for the initial relation  $h/a = 2.5$ . The 3-rd quark is o-marked as previously and the 2-nd quark is marked by the red square. The interquark distances vary in an alternating manner.

With growing the energy of the system the value  $(h/a)_{cr}$  grows. If  $h/a > (h/a)_{cr}$  the triangle orientation quasiperiodically changes (the initial counterclockwise bypass direction

<sup>3</sup> Testing the stability we, naturally, differ this problem from a uniform motion of the system c.m. that takes place if the center of masses and the rotational center in conditions (28) don’t coincide.

<sup>4</sup>Note that large disturbances, naturally, result in large changes of the motion. This fact is illustrated by the example in Fig. 3.

of the numerated quarks isn't preserved). In this motion the two nearest quarks revolve with respect to each other but don't merge.

The stability picture of the “triangle” baryon model radically differs from that for the linear configuration q-q-q where any small disturbance results in centrifugal moving away of the middle quark to one of the ends (but also without merging and with quasiperiodical return of the middle quark) [5].

It is interesting to compare these two models in the case when one of the masses  $m_i$  is larger than the sum of two others. In this case the shape of the triangle configuration for the simple rotational motion (27) tends to a rectilinear segment with the position of the largest mass at the rotational center (so the  $\Delta$  configuration practically tends to the q-q-q one) if the energy of the system decreases [9, 18].

In Fig. 6 such two motions of these two models are considered and compared. For both models the quark masses are  $m_1 = m_3 = 1$ ,  $m_2 = 3$  the tension is  $\gamma = 1$  in the “triangle” and  $\gamma = 2$  in the q-q-q configuration. The initial shape of the string is the rectilinear segment (for the  $\Delta$  configuration it is a particular case of the triangle (28) with  $h = 0$ ,  $a = 1/3$ ) rotating so that the initial velocities of the 1-st and 3-rd quarks  $v = 0.5$  are connected with  $a$  by the relation  $a = 2(m_1/\gamma)v^2/(1 - v^2)$  [1, 5]. The position of the 2-nd quark is slightly displaced with respect to the center of rotation. In Figs. 5 and 6  $\Delta t = 0.15$ .

One can see that in the “triangle” model (Figs. 6a–6c) the second (middle) heavy quark moves in the vicinity of the rotational center. In the q-q-q model (Figs. 6d–6f) the middle heavy quark moves away, then it plays a role of rotational center for the string segment between the two quarks and returns to the center of the system. The latter case demonstrates that the rotational motions of the q-q-q configuration with the middle quark at rest are unstable (unlike ones in the “triangle” model).

Note that the rotational motions (27) include a set of so called exotic states [9, 18] which contain points moving at the speed of light. Such points (cusps) with singularities of the metric  $\dot{X}^2 = X'^2 = 0$  are the typical phenomenon for the relativistic string dynamics [19]. The stability analysis of these motions needs other methods.

## Conclusion

In this paper the initial-boundary value problem for the string baryon model “triangle” is solved in general for arbitrary initial conditions. This approach let us find that the simple rotational motions (27) [9, 18] of this configuration are stable for all values of the quark masses  $m_i$  and the energy of the system.

Such a behavior radically differs from that for the linear string baryon configuration q-q-q where rotational motions are unstable [5].

Note that the initial-boundary value problem “three-string” baryon configuration is not solved yet. But the considered method after some development may be used for this model too.

The results of our analysis justify that the simple rotational states of the string model “triangle” is applicable to describing the Regge trajectories [4, 9] and give some additional arguments in favour of this model<sup>5</sup> in comparison with other string baryon models (Fig. 1).

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<sup>5</sup>There are the arguments from the baryon Wilson loop point of view in Ref. [13].

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